





Louvain

Algorithms





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DCSBM

Algorithms



SBM WalkTrap Louvain InfoMap Stability DCSBM

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Markov Chain

..., X_{past}, X_{now}, X_{future}, ...



Projection

..., Y_{past}, Y_{now}, Y_{future}, ...







Complexity







Entrogram



$$I_{0} = I(Y_{t}; Y_{t-\tau}, ...)$$

$$I_{1} = I(Y_{t}; Y_{t-2\tau}, ... | Y_{t-\tau})$$

$$I_{2}$$

$$I_{3}$$

$$I_{4}$$

$$H_{r}$$

where I(X; Y) = H(X) - H(X|Y) is the Mutual Information

M.F. et al, Journal of Complex Networks, cnx055

Entrogram





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$$I(Y_t; Y_{t-\tau}) - \alpha H(Y_t)$$

- *I*(·; ·) : Mutual Information (Markovianity of the projection)
 - au : Parameter (timescale selection)
 - H(·): Entropy (increases with the number of partitions)
 - α : Parameter (model selection)



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$$I(Y_t; Y_{t-\tau}) \propto -\sum_{rs} e_{rs} \log \frac{e_{rs}}{e_r e_s}^{\dagger}$$

† in some cases

Examples



















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Example 1. Two cycles





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VOS Crew Deploy Next Generation SVP Drifter Photo by: GDP





VOS Crew Deploy Next Generation SVP Drifter Photo by: GDP



Polar Operational Environmental Satelline Surface Velocity Program "mini" drifter In-situ observations of sea surface temperature, upper ocean currents, and other physical parameters Rick Lumpkin, NOAA/AOML



$$au=$$
 1 day





$$au = 1$$
 day





au=700 days



$$au = 1$$
 day







 $\tau = 700$ days



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- \cdot A information theoretical algorithm for block detection
- As a plus: same base as (DC)SBM
- Weighted networks and non-networks (only trajectories)
- \cdot Importance of time-scales (controlled by au)

Questions?





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